

A center curve under the Fréchet distance

Jan Hitzschke

30.03.2020

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Definition

A **curve** is a continuous map $p : [0, 1] \rightarrow \mathbb{R}^m$. Let \mathcal{C}_m be the set of all curves in \mathbb{R}^m .

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- ▶ Assume all curves to be piece-wise linear.

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Definition

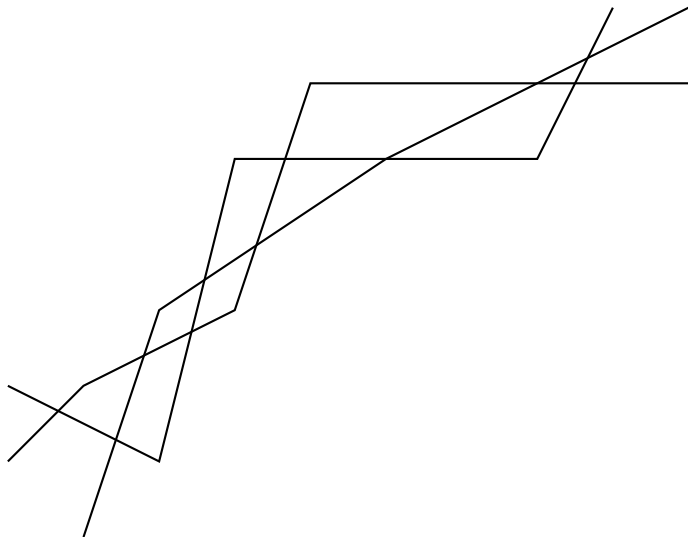
A **curve** is a continuous map $p : [0, 1] \rightarrow \mathbb{R}^m$. Let \mathcal{C}_m be the set of all curves in \mathbb{R}^m .

- ▶ Assume all curves to be piece-wise linear.

Problem

Given curves $p^1, \dots, p^n \in \mathcal{C}_m$, $r \in \mathbb{R}$ and a distance measure $d : \mathcal{C}_m^2 \rightarrow \mathbb{R}$, find a curve $q \in \mathcal{C}_m$ such that $d(p^i, q) \leq r$ or decide that none exists.

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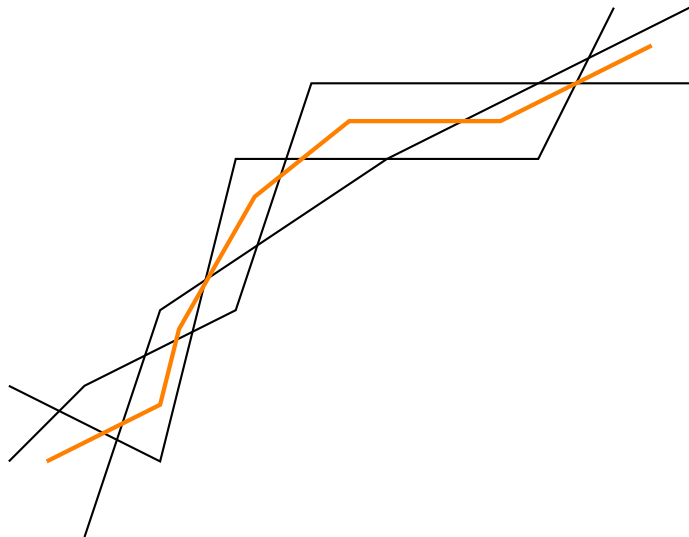
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Definition

Call a map $f : [0, 1] \rightarrow [0, 1]$ a **pace** if it is a continuous and increasing bijection. Let \mathcal{P} be the set of all paces.

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Definition

Define the **Fréchet distance** as the map $d_F : \mathcal{C}_m^2 \rightarrow \mathbb{R}$ with

$$d_F(p, q) := \inf_{f \in \mathcal{P}} \max_{x \in [0, 1]} \|p(x) - q(f(x))\|$$

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Lemma

The Fréchet distance is symmetric and satisfies the triangle inequality. It becomes a metric by setting

$$p \sim q \iff d_F(p, q) = 0.$$

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Open questions

- ▶ The Fréchet center curve problem is *NP*-hard. Is it in *NP*?
- ▶ How can the set of solutions to the problem be represented?

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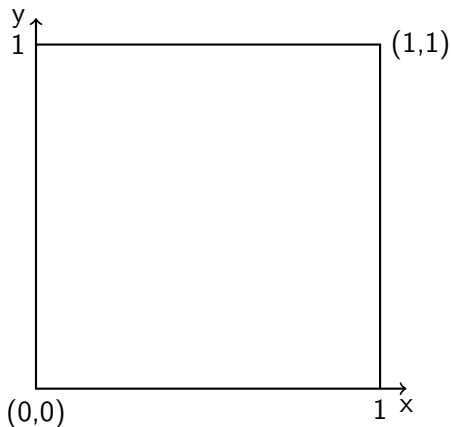
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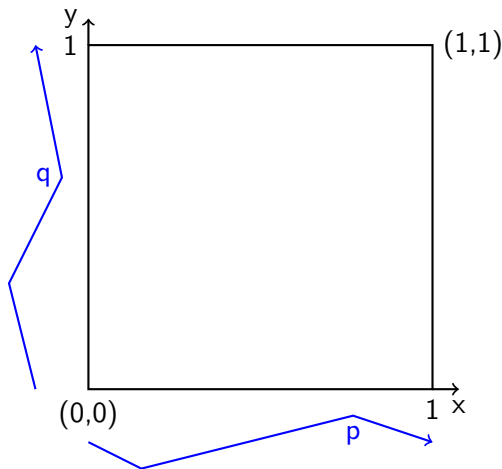
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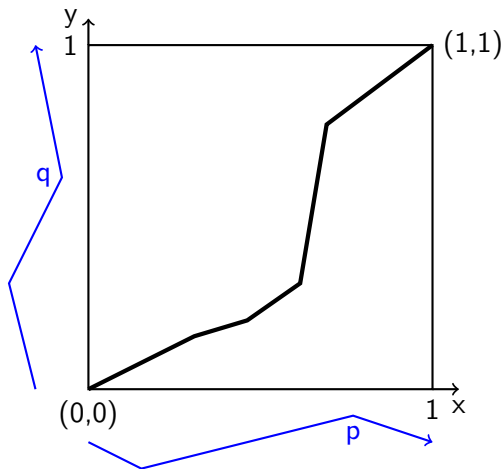


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Redefining d_F with Monotone Paths

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Definition

Call the image T of a curve $p_T : [0, 1] \rightarrow \mathbb{R}^2$ a **monotone path** if

1. $p_T(0) = (0, 0)$ and $p_T(1) = (1, 1)$
2. $x \leq y \implies p_T(x)_1 \leq p_T(y)_1$ and $p_T(x)_2 \leq p_T(y)_2$.

Denote the set of all monotone paths by \mathcal{T} .

Redefining d_F with Monotone Paths

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Denote the set of all monotone paths by \mathcal{T} .

Lemma

For any curves $p, q \in \mathcal{C}_m$ their Fréchet distance can be expressed as

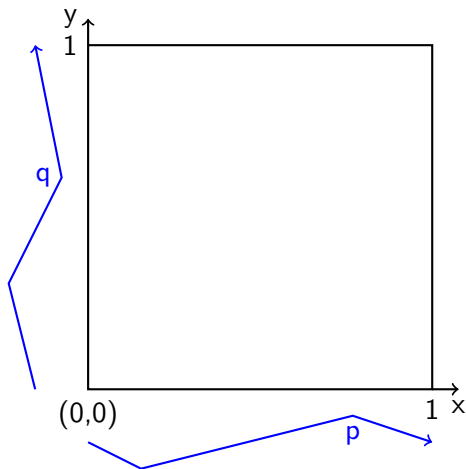
$$d_F(p, q) = \min_{T \in \mathcal{T}} \max_{t \in T} \|p(t_1) - q(t_2)\|$$

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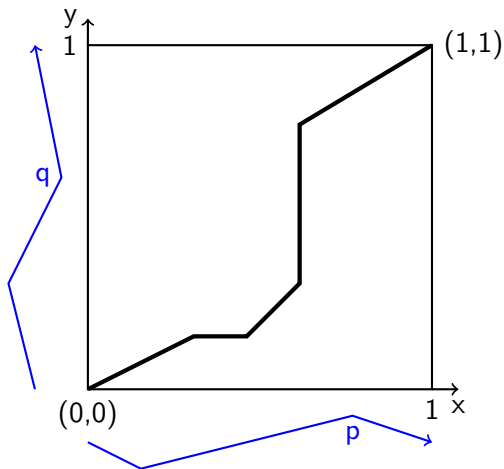
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Definition

Let p, q be piece-wise linear curves. A set $A \subset T \in \mathcal{T}$ is called a **vertex association**, if A contains a those points corresponding to vertices of either curve. Denote the set of all vertex associations by \mathcal{A} .

Vertex Associations

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Definition

Let p, q be piece-wise linear curves. A set $A \subset T \in \mathcal{T}$ is called a **vertex association**, if A contains those points corresponding to vertices of either curve. Denote the set of all vertex associations by \mathcal{A} .

Lemma

Let p, q be two piece-wise linear curves. Then

$$d_F = \min_{A \in \mathcal{A}} \max_{(x,y) \in A} \|p(x) - q(y)\|$$

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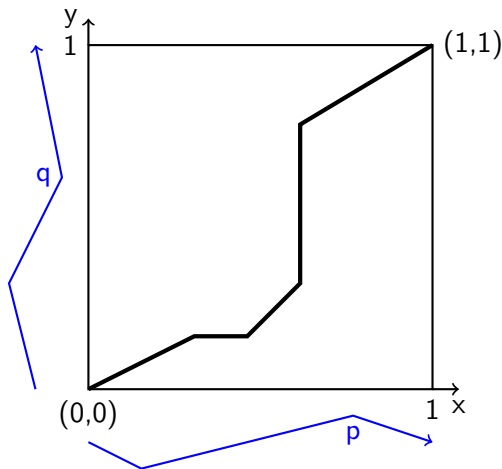
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$$d_F = \min_{A \in \mathcal{A}} \max_{(x,y) \in A} \|p(x) - q(y)\|$$



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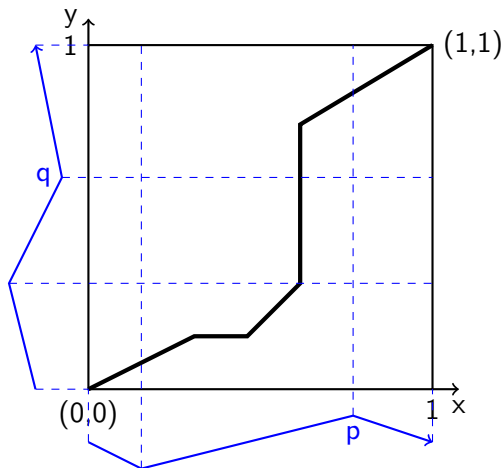
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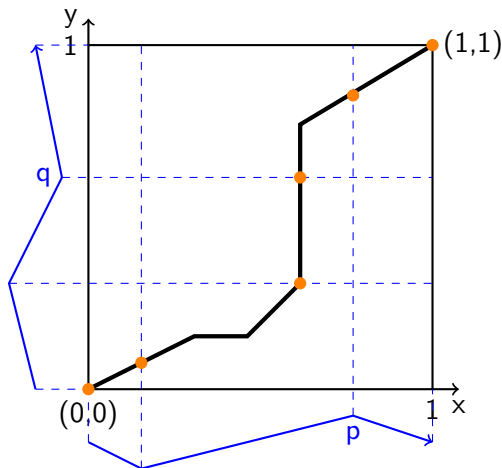
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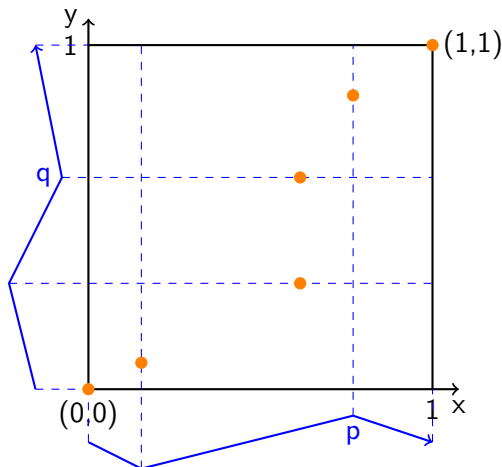
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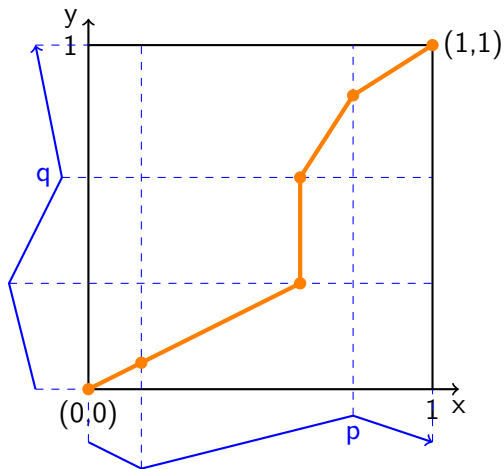
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Example: Vertex Association

$$d_F = \min_{A \in \mathcal{A}} \max_{(x,y) \in A} \|p(x) - q(y)\|$$



Lemma

Given piece-wise linear curves p^1, \dots, p^n each of length l and a center curve q of radius r , there is a curve q' with

- ▶ q' is piece-wise linear with $l' \leq nl$ vertices.
- ▶ $d(p^i, q') \leq r$ for all $i = 1, \dots, n$
- ▶ $|A^i| = l'$, i.e. each vertex of p^i associates to a vertex of q' .

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This gives an enumeration of the input vertices by the order of their associated vertices in q' .

Visiting Orders

Lemma

Given piece-wise linear curves p^1, \dots, p^n each of length l and a center curve q of radius r , there is a curve q' with

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This gives an enumeration of the input vertices by the order of their associated vertices in q' .

Definition

Given n piece-wise linear curves with l vertices each, let $N = n(l - 2)$. Then a **visiting order** Γ is a sequence $\Gamma^0, \Gamma^1, \dots, \Gamma^N \in \{1, \dots, l\}^n$ where

- ▶ $\Gamma^0 = (1, \dots, 1)$
- ▶ $\Gamma^k = \Gamma^{k-1} + e_{j_k}$.

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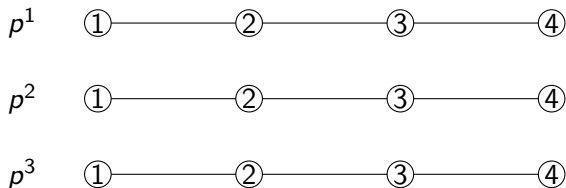
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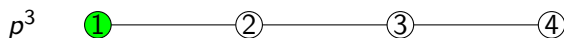
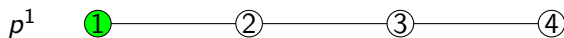
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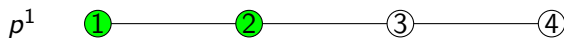


$$\Gamma^0 \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

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$$\Gamma^0 \quad \Gamma^1$$
$$\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$

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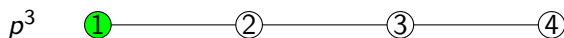
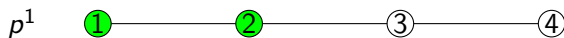
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$$\begin{array}{ccc} \Gamma^0 & \Gamma^1 & \Gamma^2 \\ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} \end{array}$$

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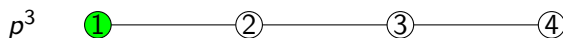
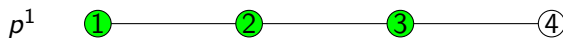
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$$\begin{array}{cccc} \Gamma^0 & \Gamma^1 & \Gamma^2 & \Gamma^3 \\ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} \end{array}$$

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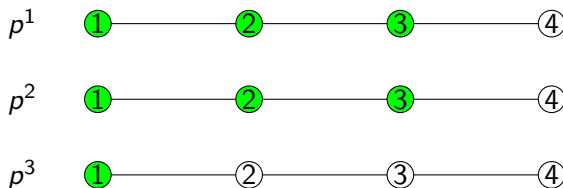
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$$\begin{array}{ccccc} \Gamma^0 & \Gamma^1 & \Gamma^2 & \Gamma^3 & \Gamma^4 \\ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} \end{array}$$

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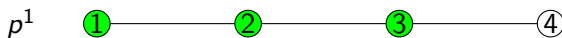
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$$\begin{array}{cccccc} \Gamma^0 & \Gamma^1 & \Gamma^2 & \Gamma^3 & \Gamma^4 & \Gamma^5 \\ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ 2 \end{pmatrix} \end{array}$$

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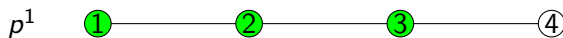
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$$\begin{array}{ccccccc} \Gamma^0 & \Gamma^1 & \Gamma^2 & \Gamma^3 & \Gamma^4 & \Gamma^5 & \Gamma^6 \\ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ 2 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ 3 \end{pmatrix} \end{array}$$

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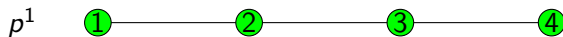
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$$\begin{array}{ccccccc} \Gamma^0 & \Gamma^1 & \Gamma^2 & \Gamma^3 & \Gamma^4 & \Gamma^5 & \Gamma^6 \\ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} & \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ 2 \end{pmatrix} & \begin{pmatrix} 3 \\ 3 \\ 3 \end{pmatrix} \end{array}$$

Preparing the variables

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- ▶ Assume to have guessed the correct visiting order Γ .

Preparing the variables

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- ▶ Denote the vertices of p^j as $p_1^j, p_2^j, \dots, p_l^j$.

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- ▶ Each q_k is associated to a point between $p_{\Gamma_i^k}^i$ and $p_{\Gamma_{i+1}^k}^i$.

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- ▶ Assume to have guessed the correct visiting order Γ .
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- ▶ Denote vertices of the center curve q as q_0, q_1, \dots, q_{N+1} .
- ▶ Each q_k is associated to a point between $p_{\Gamma_i^k}^i$ and $p_{\Gamma_i^k+1}^i$.
- ▶ The exact position can be represented by a value $\lambda_k^i \in [0, 1]$.

Preparing the variables

- ▶ Assume to have guessed the correct visiting order Γ .
- ▶ Denote the vertices of p^i as $p_1^i, p_2^i, \dots, p_l^i$.
- ▶ Denote vertices of the center curve q as q_0, q_1, \dots, q_{N+1} .
- ▶ Each q_k is associated to a point between $p_{\Gamma_i^k}^i$ and $p_{\Gamma_i^k+1}^i$.
- ▶ The exact position can be represented by a value $\lambda_k^i \in [0, 1]$.
- ▶ $\lambda_k^i = 0$ if $\Gamma_i^k - \Gamma_i^{k-1} = 1$ (say $i = j_k$).

The Inequality System

The set of solutions to the center curve problem is represented as

$$Q_{\Gamma}(p, r) = \left\{ \begin{array}{l} (q, \lambda) \in \mathbb{R}^{N \times m + n \times N} : \\ \|q_k - s_k^i\| \leq r \\ (1 - \lambda_k^i) p_{\Gamma_i^k}^i - \lambda_k^i p_{\Gamma_i^{k+1}}^i = s_k^i \\ \|q_0 - p_1^i\| \leq r \\ \|q_{N+1} - p_l^i\| \leq r \\ \lambda_k^{j_k} = 0 \\ \forall i \neq j_k \quad \lambda_{k-1}^i \leq \lambda_k^i \\ 0 \leq \lambda_k^i \leq 1 \end{array} \right.$$

where $k = 1, \dots, N$ and $i = 1, \dots, n$ in each line.

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How to solve this?

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where $k = 1, \dots, N$ and $i = 1, \dots, n$ in each line.

How to solve this?

$Q_{\Gamma}(p, r)$ is convex. \implies Use or adapt convex optimization techniques!

Relaxations

- ▶ If the λ_k^i are known, this reduces to solving $N + 2$ center problems of points.

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- ▶ If the λ_k^i are known, this reduces to solving $N + 2$ center problems of points.
- ▶ If the q_k are known, this reduces to computing n vertex associations for a given visiting order. This can be done efficiently by a greedy algorithm.

- ▶ If the λ_k^i are known, this reduces to solving $N + 2$ center problems of points.
- ▶ If the q_k are known, this reduces to computing n vertex associations for a given visiting order. This can be done efficiently by a greedy algorithm.
- ▶ If the constraints $\lambda_{k-1}^i \leq \lambda_k^i$ are dropped, all q_k are independent from each other.
 \implies Each is the solution to a center problem of points and lines.

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Separation

Each inequality constraining $Q(p, r)$ can be made into a polynomial time separation oracle.
(But not if r was a variable!)

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Separation

Each inequality constraining $Q(p, r)$ can be made into a polynomial time separation oracle.
(But not if r was a variable!)

Proof.

Given a vector y the constraint $y^T x \leq r^2$ can be checked efficiently.

If $\|y\| > r$, for any $x \in Q_\Gamma(p, r)$, by Cauchy-Schwarz:

$$y^T x \leq \|y\| \|x\| \leq \|y\| r < \|y\|^2 = y^T y$$



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We can use the ellipsoid method

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□

We can use the ellipsoid method

to get a point $x \in Q_\Gamma(p, r)$ or decide that $\text{vol}(Q_\Gamma(p, r)) < C$ for any $C > 0$.

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- ▶ Let $Q_{\Gamma}^{\epsilon}(p, r)$ result from $Q_{\Gamma}(p, r)$ by increasing all right hand sides by ϵ .

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- ▶ Let $Q_{\Gamma}^{\epsilon}(p, r)$ result from $Q_{\Gamma}(p, r)$ by increasing all right hand sides by ϵ .
- ▶ If $Q_{\Gamma}(p, r) \neq \emptyset$, then $\text{vol}(Q_{\Gamma}^{\epsilon}(p, r)) \geq C(m, \epsilon)$.

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- ▶ Let $Q_{\Gamma}^{\epsilon}(p, r)$ result from $Q_{\Gamma}(p, r)$ by increasing all right hand sides by ϵ .
- ▶ If $Q_{\Gamma}(p, r) \neq \emptyset$, then $\text{vol}(Q_{\Gamma}^{\epsilon}(p, r)) \geq C(m, \epsilon)$.
- ▶ If $x \in Q_{\Gamma}^{\epsilon}(p, r)$ is found, then $x \in Q_{\Gamma}(p, r + \epsilon)$ with small changes.

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- ▶ Let $Q_{\Gamma}^{\epsilon}(p, r)$ result from $Q_{\Gamma}(p, r)$ by increasing all right hand sides by ϵ .
- ▶ If $Q_{\Gamma}(p, r) \neq \emptyset$, then $\text{vol}(Q_{\Gamma}^{\epsilon}(p, r)) \geq C(m, \epsilon)$.
- ▶ If $x \in Q_{\Gamma}^{\epsilon}(p, r)$ is found, then $x \in Q_{\Gamma}(p, r + \epsilon)$ with small changes.

Theorem

For inputs p, r , fixed visiting order σ and $\epsilon > 0$ there is a polynomial time algorithm that

- ▶ gives a center curve with radius $\leq r + \epsilon$ or
- ▶ decides there is no center curve of radius r .

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Lemma

Each linear closed constraint of a closed convex set P is attained with equality by some point $x \in P$ unless it is redundant.

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Lemma

Each linear closed constraint of a closed convex set P is attained with equality by some point $x \in P$ unless it is redundant.

Proposition

By guessing which are attained as equalities, all linear inequalities constraining $Q_{\Gamma}(p, r)$ can be transformed or removed.

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By guessing which are attained as equalities, all linear inequalities constraining $Q_{\Gamma}(p, r)$ can be transformed or removed.

Question

Can a similar thing be done for nonlinear inequalities?

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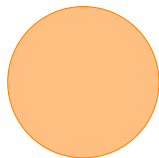
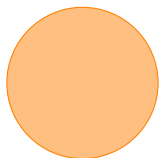
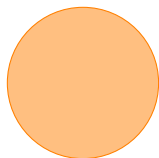
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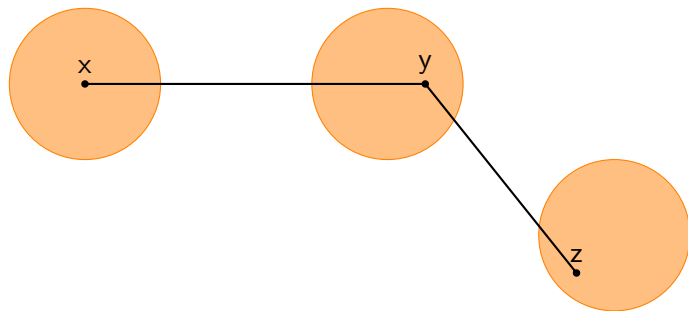
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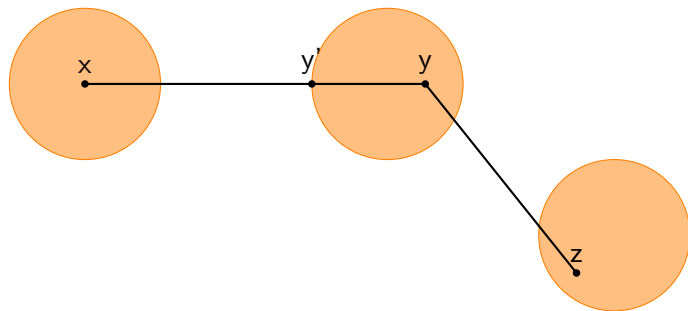
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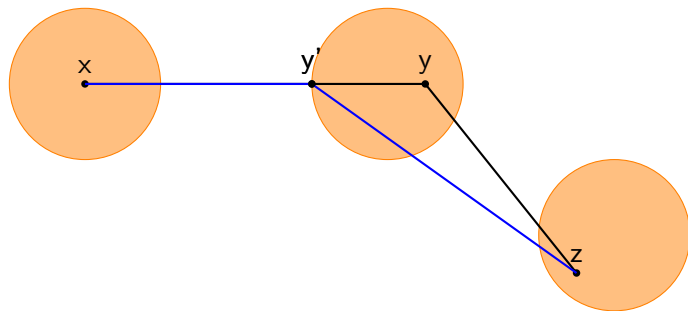
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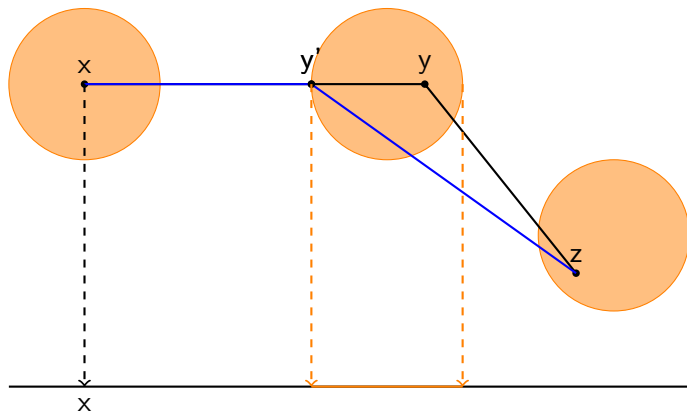
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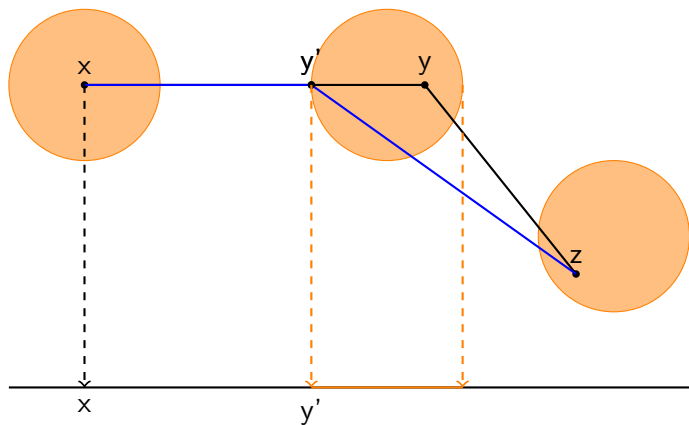
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Lemma

A center curve q can be chosen such that for all $k = 1, \dots, N$, one of the conditions $q_k = q_{k-1}$ or $\|q_k - p_{\Gamma_{\sigma_k}^{\sigma_k}}^{\sigma_k}\| = r$ is satisfied.

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A center curve q can be chosen such that for all $k = 1, \dots, N$, one of the conditions $q_k = q_{k-1}$ or $\|q_k - p_{\Gamma_k}^{\sigma_k}\| = r$ is satisfied.

Fact

For a point $y \in \mathbb{R}$, there are exactly two points $y_1 < y_2 \in \mathbb{R}$ with $|y_i - y| = r$ for any $r > 0$.

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Lemma

A center curve q can be chosen such that for all $k = 1, \dots, N$, one of the conditions $q_k = q_{k-1}$ or $\|q_k - p_{\Gamma_{\sigma_k}^{\sigma_k}}\| = r$ is satisfied.

Fact

For a point $y \in \mathbb{R}$, there are exactly two points $y_1 < y_2 \in \mathbb{R}$ with $|y_i - y| = r$ for any $r > 0$.

Idea

Build the center curve iteratively by either staying at the current vertex or moving to the closer one of the two candidates.

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Theorem

Given curves p^1, \dots, p^n in \mathbb{R} and $r \geq 0$, a curve q can be computed in time $O(N)$ such that q is a center curve with radius r if one exists.

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Lemma

Whether $d_F(p^i, q) \leq r$ can be checked in polynomial time.

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Lemma

Given n curves with l vertices each, the number $|\mathcal{V}|$ of possible visiting orders is $|\mathcal{V}| = \frac{N!}{(l-2)!^n}$.

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Lemma

For this number, there are bounds

$$\left(\frac{n}{2}\right)^{N-n} \leq |\mathcal{V}| \leq n^N$$

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- ▶ An algorithm trying all visiting orders can have exponential, but no polynomial runtime.

Counting Visiting Orders

Lemma

Given n curves with l vertices each, the number $|\mathcal{V}|$ of possible visiting orders is $|\mathcal{V}| = \frac{N!}{(l-2)!^n}$.

Lemma

For this number, there are bounds

$$\left(\frac{n}{2}\right)^{N-n} \leq |\mathcal{V}| \leq n^N$$

- ▶ An algorithm trying all visiting orders can have exponential, but no polynomial runtime.
- ▶ Is there a way to not test every single visiting order?

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Definition

Given curves p^1, \dots, p^n their n -wise Fréchet distance is defined as

$$d_F(p^1, \dots, p^n) = \inf_{f_1, \dots, f_n \in \mathcal{P}} \max_{1 \leq i, j \leq n} \max_{x \in [0, 1]} \|p^i(f_i(x)) - p^j(f_j(x))\|$$

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- ▶ Strong connection to center curve problem.

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- ▶ Strong connection to center curve problem.
- ▶ Admits same theory up to visiting orders.

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- ▶ Strong connection to center curve problem.
- ▶ Admits same theory up to visiting orders.
- ▶ Can be solved by guessing v.o. and checking a center curve candidate.

n -wise Fréchet distance

Definition

Given curves p^1, \dots, p^n their n -wise Fréchet distance is defined as

$$d_F(p^1, \dots, p^n) = \inf_{f_1, \dots, f_n \in \mathcal{P}} \max_{1 \leq i, j \leq n} \max_{x \in [0, 1]} \|p^i(f_i(x)) - p^j(f_j(x))\|$$

- ▶ Strong connection to center curve problem.
- ▶ Admits same theory up to visiting orders.
- ▶ Can be solved by guessing v.o. and checking a center curve candidate.
- ▶ The n -wise distance is at most twice the center curve radius.

n -wise Fréchet distance

- ▶ A vertex association can be computed iteratively for any visiting order, even if it is a partial order.

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n -wise Fréchet distance

- ▶ A vertex association can be computed iteratively for any visiting order, even if it is a partial order.
- ▶ The n -wise distance on a partial order is a lower bound to the distance on any extension of that order.

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- ▶ A vertex association can be computed iteratively for any visiting order, even if it is a partial order.
- ▶ The n -wise distance on a partial order is a lower bound to the distance on any extension of that order.
- ▶ \implies The n -wise distance can be decided by Branch-and-Bound on visiting orders.

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- ▶ A vertex association can be computed iteratively for any visiting order, even if it is a partial order.
- ▶ The n -wise distance on a partial order is a lower bound to the distance on any extension of that order.
- ▶ \implies The n -wise distance can be decided by Branch-and-Bound on visiting orders.
- ▶ Using $2r$ as a bound allows to decide if a visiting order could attain center curve radius r .

Thank you for listening!